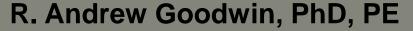
Predicting near-future juvenile salmon response to

water management and engineered structures across diverse tidal river conditions

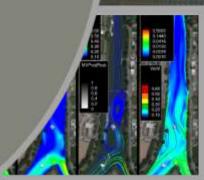


U.S. Army Engineer R&D Center Portland, Oregon

Collaborators & Contributors

Many, many, ...

18 May 2023





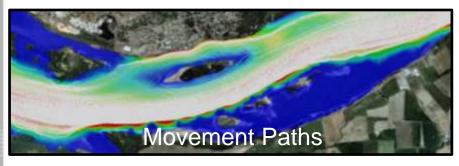


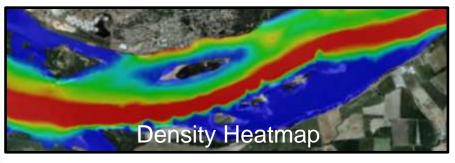




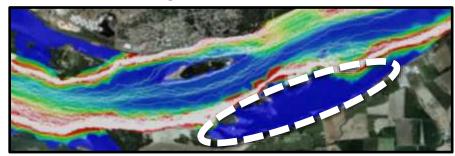
ELAM model: Peer-reviewed Fish Prediction

Water Flow Particles

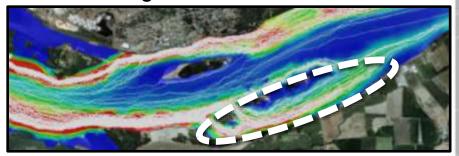




Species Movement Forecast w/out engineered modification



w/engineered modification

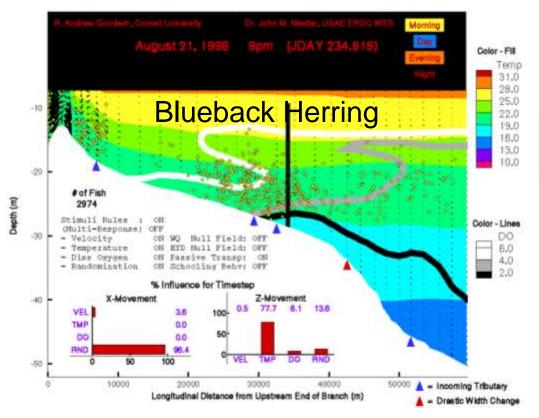


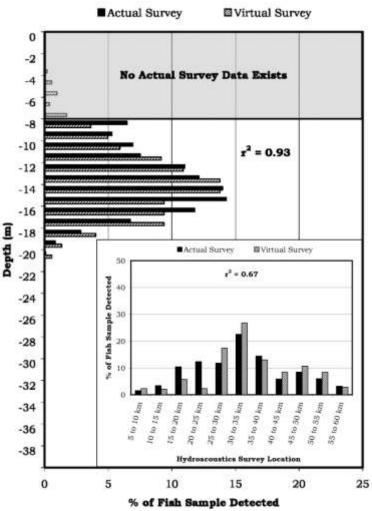
Habitat Selection / Species Distribution

-25 years ago

- Temperature
- Dissolved oxygen
- 2-D hydrodynamics

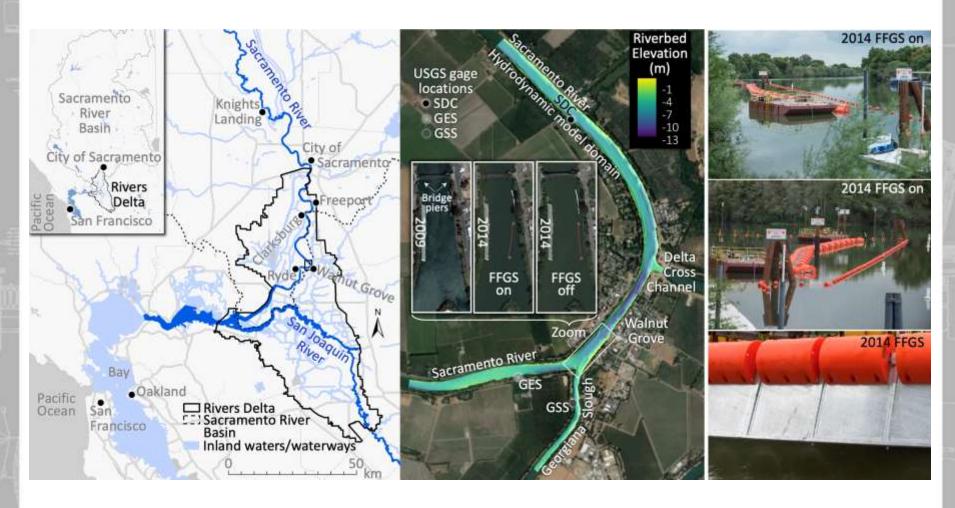
CE-QUAL-W2





25 Years: Out-of-Sample Fish 3-D Movement Prediction Hydraulic + Individual- (Agent-) based Modeling w/cognition for engineering design (Years 2003-10) Columbia Proceedings of the **Year 2014** National Academy of Sciences of the United States of America Year 2000 Fish navigation of large dams emerges from their modulation of flow field experience R. Andrew Goodwin^{1,1}, Marcela Politano⁶, Justin W. Garvin⁷, John M. Nestler⁸, Duncan Hay⁸, James J. Anderson¹, Larry J. Weber^b, Eric Dimperio^a, David L. Smith^d, and Mark Timko^a Entrainment Cornell Forecasting 3-D fish movement behavior using a Eulerian-Lagrangian-agent method (ELAM) R. Andrew Goodwin * A. B., John M., Nestler * 1 B., James J. Anderson 4 7 B., Larry J., Weber 4 1 B., Daniel P. Loucks 5

Tidal Sacramento River at Georgiana Slough



Tidal Sacramento River at Georgiana Slough

frontiers
in Ecology
and Evolution

Behavioral and Evolutionary Ecology

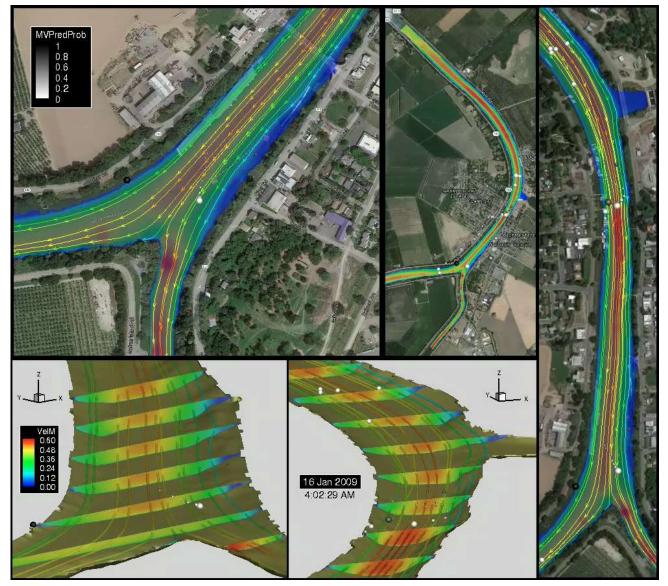
Predicting near-term, out-of-sample fish passage, guidance, and movement across diverse river environments by cognitively relating momentary behavioral decisions to multiscale memories of past hydrodynamic experiences

R. Andrew Goodwin^{1,7}, Yong G. Lai², David E. Taffin³, David L. Smith⁴, Jacob McQuirk⁵, Robert Trang⁵, and Ryan Reeves⁵

- Updated cognitive-based algorithms for predicting fish movement, guidance, and entrainment
- Simplest formulation of many evaluated
- Behaviors emerge from animal's recent past experience (environmental context)
- Selective tidal stream transport a superset of the behaviors at large hydropower dams – potential for unified prediction model



Tidal Sacramento River at Georgiana Slough

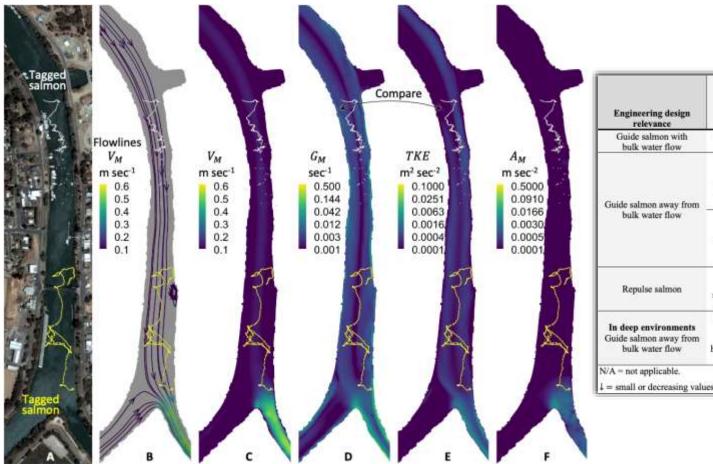


U2RANS CFD - Yong Lai, USBR // Acoustic-tag Telemetry - USGS

Fish Behavior is Complex – Different Movement Modes

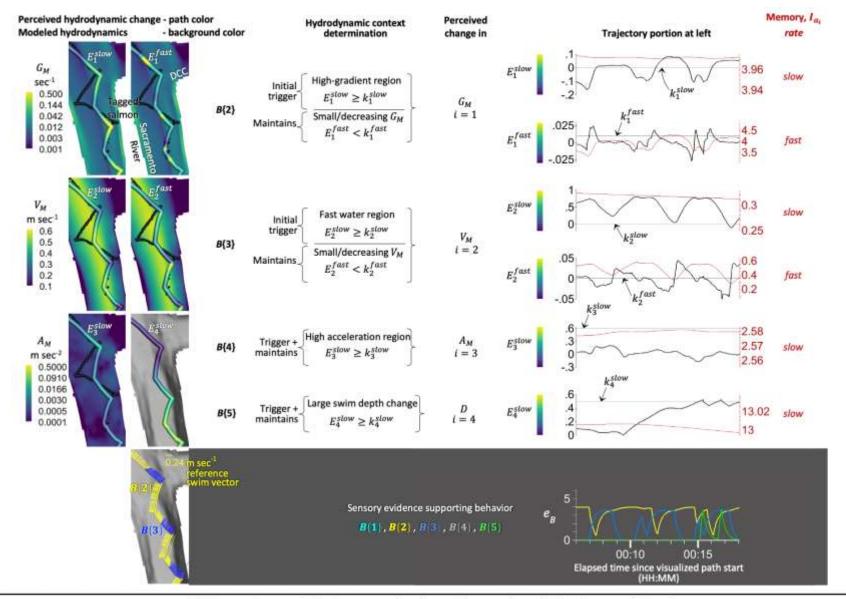


Hydrodynamic Behavioral Stimuli

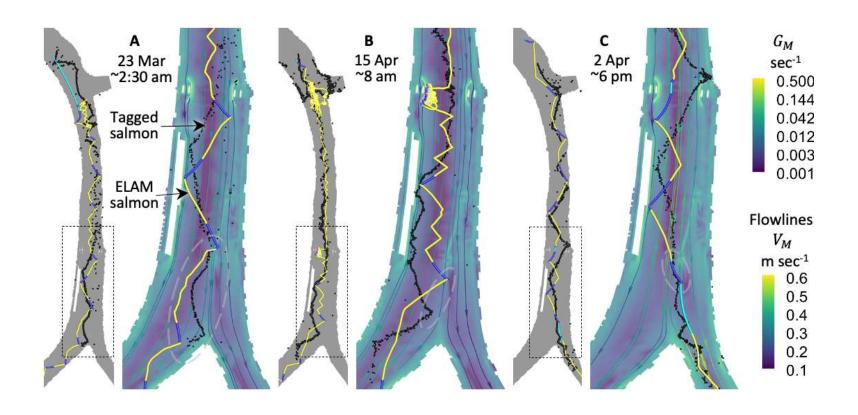


Engineering design relevance	Orientation Alignment Attraction Repulsion Modulation	Trigger Accumulated sensory evidence, e _g , indicates
Guide salmon with bulk water flow	Flowline alignment swim with flow	Absence of other triggers
Guide salmon away from bulk water flow	Velocity (V _M) attraction swim toward fastest water	Small or decreasing perceived change in spatial gradient of wate speed G_M (4 E_1^{fast}) in large G_M (7 E_2^{glow})
	Gradient (G _M) attraction swim toward largest spatial gradient in water speed	Small or decreasing perceived change in water speed V_H $(1 E_2^{fast})$ in fast water $(7 E_2^{stow})$
Repulse salmon	Acceleration (A_M) repulsion swim against flowline, away from large A_M	Large perceived change in water acceleration/deceleration A_M († E_3^{slow})
In deep environments Guide salmon away from bulk water flow	Pressure (depth, D) modulation swim toward habituated/acclimatized depth	Large perceived change in swim bladder pressure or depth D $(\uparrow E_4^{zlow})$

Perceptual Decision-Making (Cognition)



Out-of-Sample Movement Prediction



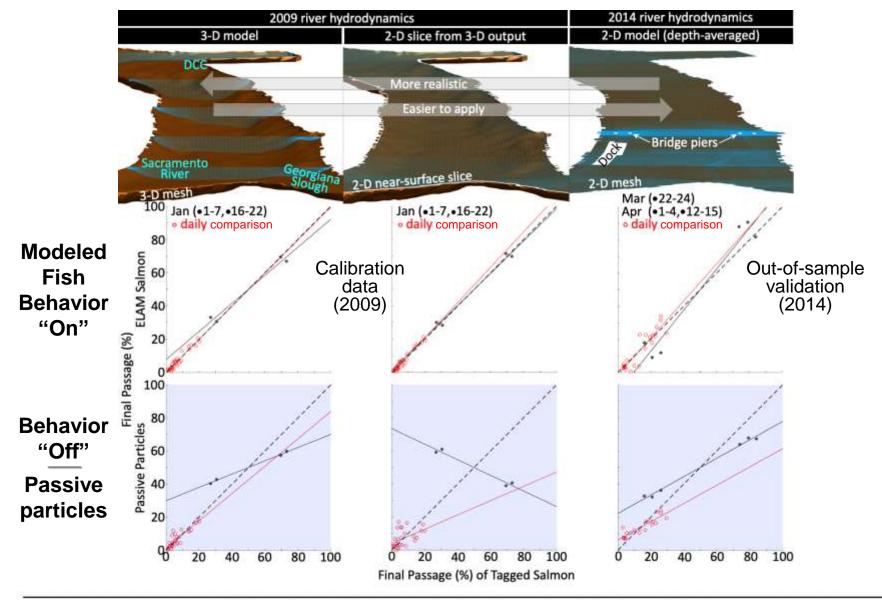
 $B{1}$: flowline alignment

 $B\{2\}$: velocity (V_M) attraction

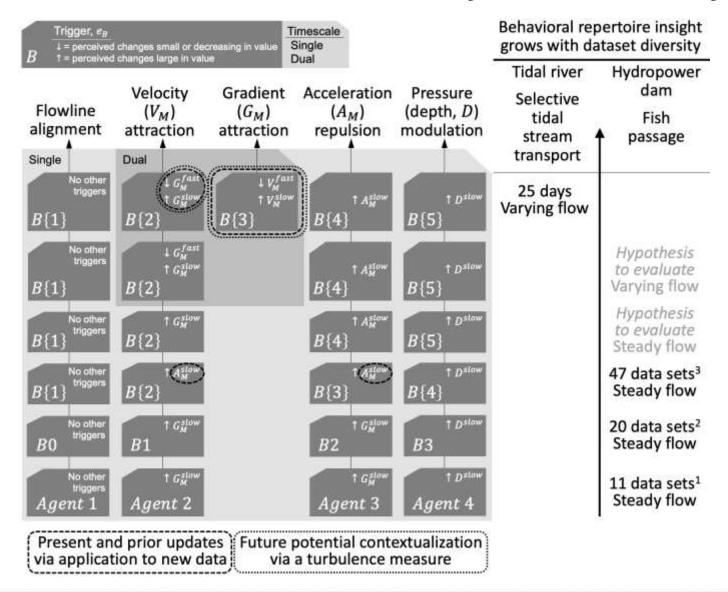
B{3}: gradient (G_M) attraction

 $B{4}$: acceleration (A_M) repulsion

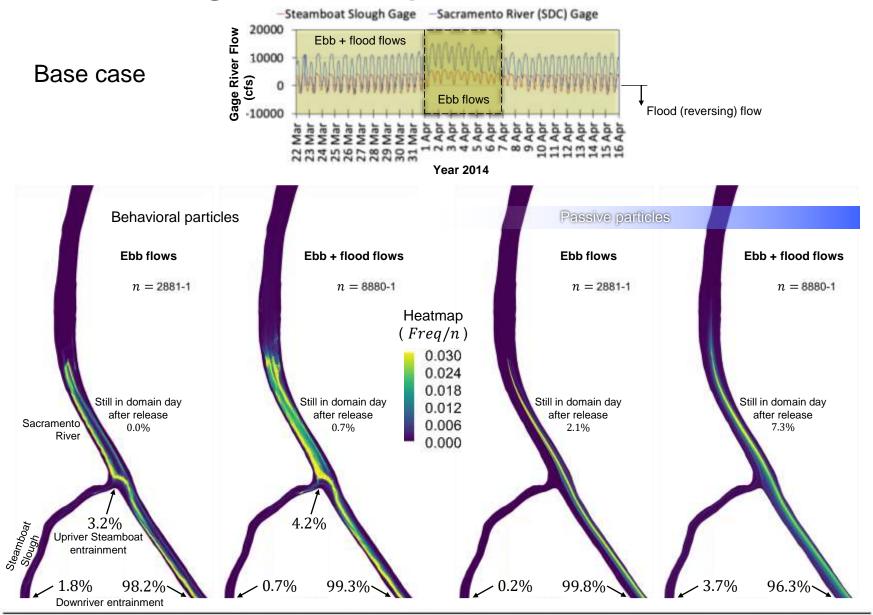
Predicting Out-of-Sample Guidance/Entrainment



What \$65+ Million of Telemetry & CFD is Saying



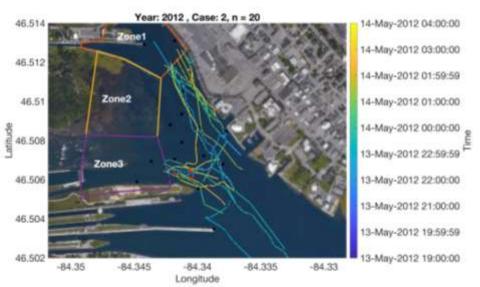
Predicting Out-of-Sample Guidance/Entrainment

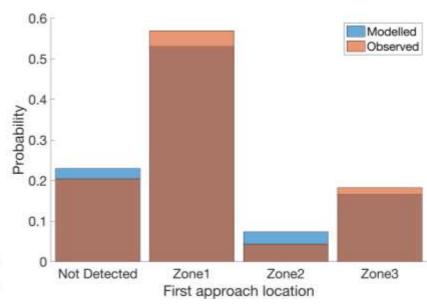


Predicting Upstream-migrating Invasive Lamprey Laurentian Great Lakes

Fish orientation

- *V_M*-dependent
- Conditional on lower G_M while experiencing above a certain threshold

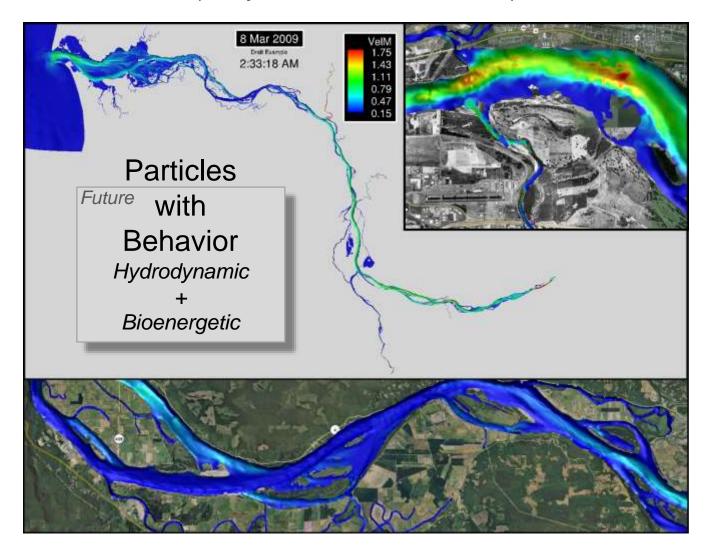




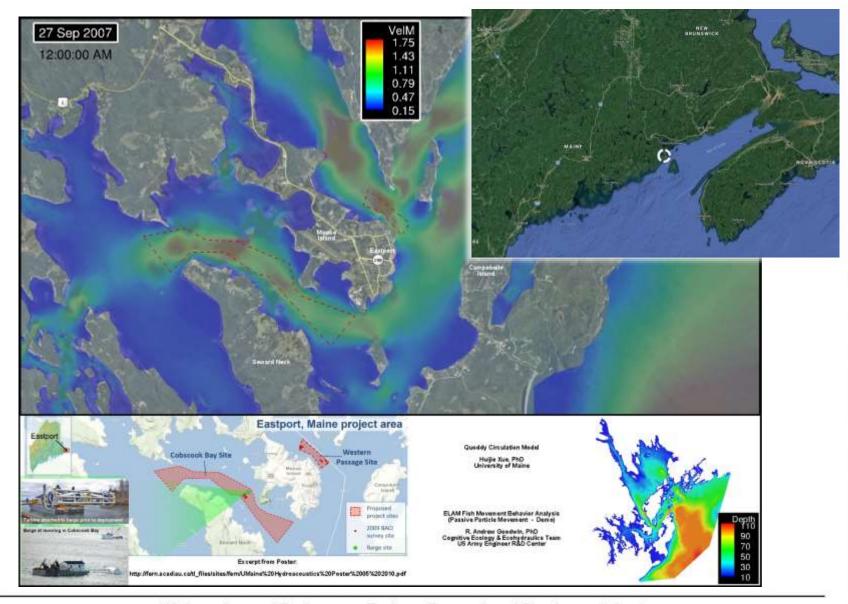
James Kerr University of Guelph

River / Estuary Restoration

(Project & Reach Scales)



Tidal Estuary Renewable Energy



ELAM Theory-Informed Machine Learning

Real-time Fish Trajectory Prediction



Boardman River, Michigan Great Lakes Fishery Commission

Bi-directional, selective fish passage

